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## ON THE BUFFING PROCESS CAUSED BY THE SHOCK THAT APPEARS IN THE USE OF RAILWAY VEHICLES

The paper presents an experimental study on the appreciation of the values of forces that strain the bearing structures of railway vehicles during the shock caused by collision. For this purpose, a force transducer was designed and executed that measures force on three orthogonal directions, which was inserted on the king-pin bearing beam of the railway car's bogie. The theoretical computation methods for the forces that appear on the car during the shock caused by collision were verified through experimental measurements, with the resulting conclusions.

### 1. Theoretical Considerations

During the shock caused by collision, the longitudinal force  $F$ , applied through the shock insulators (buffers, central coupling dampeners) acts on the vehicle. At the same time, due to the accelerations transmitted to the vehicles, the following inertia forces appear [1], [2], [3], [4], [6], [8], [10] figure 1:

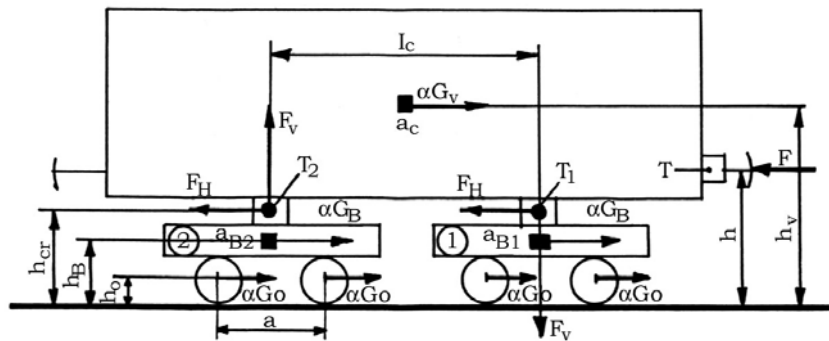


Figure 1 – Forces that act on the vehicle during the collision and transducers used for experimental determinations (T, T1, T2 – force transducers; aC, aB1, aB2 acceleration transducers)

1.  $F_{iV}$  – inertia force of the mass and weight  $G_V$  of the carbody and load of the vehicle:

$$F_{iV} = \alpha G_V \quad (1)$$

2.  $F_{iB}$  – inertia force of the mass and suspended weight of the bogie  $G_B$ :

$$F_{iB} = \alpha G_B \quad (2)$$

3.  $F_{iO}$  – inertia force of the mass and weight of the axle  $G_O$ :

$$F_{iO} = \alpha G_O \quad (3)$$

Theoretically,  $\alpha$  is considered as being a proportionality coefficient equal to:

$$\alpha = \frac{a}{g} \quad (4)$$

where:

- $a$  is the transmitted acceleration;
- $g$  is the gravitational acceleration.

The magnitude of the proportionality coefficient  $\alpha$  depends on the specific energy factor  $2\beta$ , in the sense that its values decrease with the increase of  $2\beta$ . The energy factor  $2\beta$  is defined as [4]:

$$2\beta = \frac{W_e}{E_p} \quad (5)$$

where:

- $W_e$  – potential deformation energy stored by the shock insulators (buffers, central coupling);
- $E_p$  – total stored potential deformation energy.

$$E_p = \frac{m_1 m_2}{m_1 + m_2} \frac{v^2}{a} = W_e + W_{eo} + W_{ev} + W_{eB} \quad (6)$$

where:

- $W_{e\hat{1}}$  – potential deformation energy stored by the freight;
- $W_{ev}$  – potential deformation energy stored by the bearing structure of the vehicle;
- $W_{eB}$  – potential deformation energy stored by the bearing structure of the bogies.

Thus, the equation becomes:

$$1 = \frac{W_e}{E_p} + \frac{W_{eo}}{E_p} + \frac{W_{ev}}{E_p} + \frac{W_{eB}}{E_p} \quad (7)$$

The proportionality coefficient  $\alpha$  is obviously dependent on the value of the energy factor  $2\beta$ , consequently on the quantity of potential deformation energy stored by the shock insulators that serve the purpose of diminishing the response of the considered mechanical system (transmitted acceleration and forces) to the shock caused by collision.

Figure 1 shows the inertia forces applied in their gravity centers and their distances from the railway.

The force transmitted during shock,  $F$ , is equal to:

$$F = F_{iV} + 2F_{iB} + 4F_{iO} \quad (8)$$

On each bogie there acts:

a) a horizontal component  $F_H$  and a vertical one  $F_V$  of the force that represents the reaction of the carbody in the bogie-chassis connection.

$$F_H = F_{iB} + 2F_{iO} \quad (9)$$

and:

$$F_V = \frac{F_{iV}(h_V - h) - 2F_{iB}(h - h_B) - 4F_{iO}(h - h_O)}{l_C} \quad (10)$$

where:

- $h$  is the distance of the force  $F$  from the railway;
- $h_V$ ,  $h_B$ ,  $h_O$  are the distances of the gravity centers of the carbody and freight, suspended part of the bogie and vehicle's axles from the railway;
- $l_C$  vehicle axle base.

During the shock, the first bogie is additionally loaded with the value  $F_V$ , while the second is correspondingly unloaded.

b) inertia forces applied in the axis of each beam of the bogie  $F_{iB}/2$  and in each axle box  $F_{iO}/2$ .

c) forces that represent the vertical reaction transmitted to the suspension from each wheel.

$$F_S = \frac{F_V}{4} \pm \frac{F_H(h_{Cr} - h_O) - F_{iB}(h_B - h_O)}{2a} \quad (11)$$

where:

- $h_{Cr}$  is the distance of the bogie-chassis connection in relation to the railway;
- $a$  bogie axle base.

For the vertical reaction transmitted to the suspension, the minus sign is adopted for the first and the plus sign for the second.

## 2.Experimental Testing

In order to experimentally determine the proportionality coefficient  $\alpha$  and the components  $F_H$  and  $F_V$  collision testing was conducted under the following conditions [4], [8], [9]:

1. Colliding car with mass  $m_1 = 80t$  collided a car with mass  $m_2 = 25,5t$ , resting and unbraked, at collision velocities between (6,0 - 11,6)km/h.

2. The collided car had two bogies equipped with specially constructed force transducers, of own design [2], [5], [7], [11] fig. 2, mounted on the king-pin beam, fig. 3 and fig. 4. The force transducers  $T_1, T_2$ , which measure the force on three orthogonal directions, were placed in such a manner as to determine the forces on the longitudinal direction  $F_{H1}, F_{H2}$ , and vertical  $F_{V1}, F_{V2}$ , of the first and second bogie.

3. Figure 2 shows the used transducers.



Figure 2 – Force transducer for three orthogonal directions



Figure 3 – Moment from the assembly of the force transducer in the king-pin bearing beam



Figure 4 – Moment from the assembly of the force transducer in the king-pin bearing beam

For example, for the case of the collision at velocity  $v=11,6\text{km/h}$  the determined parameters were:

- force transmitted through buffers  $F = 1060,5\text{KN}$ ;
- longitudinal acceleration of bogie 1 and 2  $a_{B1} = 6,01\text{g}$  and  $a_{B2} = 6,31\text{g}$ , respectively;
- acceleration of the carbody  $a_C = 6,15\text{g}$ ;
- vertical component of bogie 1 and 2  $F_{V1} = 135\text{KN}$ ;  $F_{V2} = 80\text{KN}$ , respectively;
- horizontal component of bogie 1 and 2  $F_{H1} = 160\text{KN}$ ;  $F_{H2} = 100,8\text{KN}$ , respectively.

### 3. Conclusions

1. From the measurements of the longitudinal accelerations of the bogies, the proportionality coefficient results as  $\alpha_{B1}=6,01$  for the first bogie, and  $\alpha_{B2}=6,31$  for the second. Since the weight of the bogie was  $G_B=4550\text{kg}$ , the values of the horizontal forces result as  $F_{H1}=273,4\text{KN}$ , and  $F_{H2}=287,0\text{KN}$ .

2. The experimentally determined values, using the force transducers  $T_1$  and  $T_2$ , for the horizontal components  $F_{H1}$  and  $F_{H2}$  are significantly lower than those resulting from using the proportionality coefficients  $\alpha_{B1}$  and  $\alpha_{B2}$  determined by measuring the accelerations on the longitudinal direction  $a_{B1}$  and  $a_{B2}$ . It is observed that  $F_{H1} > F_{H2}$ .

3. The values of the vertical forces determined experimentally, confirm the supplementary vertical loading of the first bogie by  $F_{V1}=135\text{KN}$  and the almost complete unloading of the second bogie by  $F_{V2} = - 80\text{KN}$ .

4. Using the proportionality coefficients  $\alpha_{B1}$ ,  $\alpha_{B2}$  of the bogies, and  $\alpha_C=6,15$  of the carbody, the vertical component  $F_V = 58,24\text{KN}$  was determined using equation (10). A large difference is observed between the values of the vertical forces measured experimentally with force transducers and the values determined with the proportionality coefficients  $\alpha_{B1}$ ,  $\alpha_{B2}$  and  $\alpha_C$ .

5. The proportionality coefficient, theoretically accepted as being the ratio between the acceleration transmitted to the vehicle and the gravitational acceleration, can not be used under this form for the theoretical computations of the forces  $F_H$ ,  $F_V$ ,  $F_{iV}$ ,  $F_{iB}$ ,  $F_{iO}$ ,  $F_S$ ,  $F$ .

6. Experimentally, a superior loading is observed vertically  $F_{V1}$  and horizontally  $F_{H1}$ , for bogie 1. Bogie 2, upon application of the force transmitted to the car,  $F$ , during collision, has the tendency to completely unload vertically, being necessary to investigate the behaviour of the bogie-chassis connection for the collision of the empty car state. In this situation, the weight of the car acting on the bogie  $G_V/2$  can be cancelled by the vertical component  $F_{V2}$  that acts in the opposite direction.

7. The strains of the bearing structures of the bogies during the collision process are determined by:

- Horizontal force  $F_H$ , applied in the bogie-chassis connection;
- Vertical force  $(G_V/2 \pm F_V)$ , applied in the bogie-chassis connection;
- The moment due to the inertia forces of the suspended masses of the the bogie  $F_{iB}$  and the force  $F_H$ , which vertically load the second axle of the bogie while unloading the first one, in the support of the bogie frame on the suspension, with the value:

$$F_s^* = \pm \frac{F_H(h_{Cr} - h_o) - F_{iB}(h_B - h_o)}{2a} \quad (12)$$

8. The strains of the resistance structure of the carbody during the collision process are determined by:

- Weight of the carbody and freight  $G_V = G_C + G_f$ ;
- force  $F$  transmitted through the shock insulators to the carbody;
- inertia force  $F_{iV}$  due to the weight of the carbody  $G_C$  and the transported freight  $G_f$ ;
- forces  $F_H$  and  $F_V$ , applied in the bogie-chassis connection.

Further studies will establish the dependency relationship between the proportionality coefficient  $\alpha$  and the energy factor  $2\beta$ .

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