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The method of analysis of nonlinear dynamics and stability of the powder materials' shells and pressforms during the processes of their forming and various thermo-forced loadings is proposed. One may account with the help of this method various nonlinear elastic properties of the material and short-time' changes of the loading fields' properties as well.

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531 + 535.39 + 539.3

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 $(t_0 = 1...10),$









$$\begin{cases} div\vec{u} = \frac{x}{(\frac{1}{2}+2-\gamma)} \cdot T; \\ \Delta T - \frac{1}{c_0^{-2}} \cdot \frac{\partial T}{\partial t} - \frac{1}{c^2} \cdot \frac{\partial^2 T}{\partial t^2} = 0. \end{cases}$$
(3)
$$(3) \qquad (1) \qquad (1) \qquad (2) \qquad (3) \qquad (4) \qquad (3) \qquad (4) \qquad (3) \qquad (4) \qquad (5) \qquad (4) \qquad (4) \qquad (5) \qquad (4) \qquad (4) \qquad (5) \qquad (4) \qquad (5) \qquad ($$



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$$+\frac{2\cdot\ldots\cdot(1-2\dagger)\cdot(1+\dagger)}{E}\cdot(\vec{g}-\vec{u}) = \frac{2\mathbf{r}\cdot(1+\dagger)}{3}\cdot\nabla T,$$
⁽⁹⁾

$$E - (()), \vec{y} = \frac{\partial^{2} \vec{u}}{\partial t^{2}}, \qquad : \frac{u}{c_{l}^{2} \cdot t^{2}} << \frac{\Gamma \cdot T}{L}, \quad c_{l} - \frac{1}{c_{l}}, \quad$$

$$\frac{\partial T}{\partial t} = \mathbf{t} \cdot \Delta T - \mathbf{f} \cdot \frac{\partial^2 T}{\partial t^2}, \quad V^2 = \frac{\mathbf{t}}{\mathbf{f}}, \tag{12}$$

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$$\begin{bmatrix} 6 \\ (& V &), \\ , & [7] & . & . \\ , & q & S & . \\ , & q & S & . \\ , & [12], & [8], & : \\ & \frac{\partial T}{\partial t} = \overline{\tau} \cdot \Delta T - \frac{\overline{\tau}}{\overline{V}^2} \cdot \frac{\partial^2 T}{\partial t^2}; \quad \overline{\tau} = \frac{3 \cdot (1 - \overline{\tau}) \cdot \overline{\Gamma}}{[(1 + \overline{\tau}) \cdot C_p + 2 \cdot (1 - 2\overline{\tau}) \cdot C_v]}; \quad (13) \\ & \overline{V}^2 = \frac{\overline{\tau}}{\overline{\tau}}. & \\ (& , & [8] & \overline{\Gamma} = k). \\ & (& , & [8] & \overline{\Gamma} = k). \\ & (& , & [8], & \overline{\Gamma}_0 & \\ & T, & . & T_0 & \\ & (& , & [8]), & [6], & . \\ & \vdots & \\ & \frac{\partial T}{\partial t} = \overline{\tau} \cdot \Delta T - \overline{\tau} \cdot \frac{\partial^2 T}{\partial t^2}. & (14) \\ & \vdots & & \\ & (&), & \vdots & \\ & \frac{\partial T}{\partial t} = \overline{\tau} \cdot \Delta T - \overline{\tau} \cdot \frac{\partial^2 T}{\partial t^2}, \quad \overline{\tau} = \frac{\overline{\tau}}{C_p} = \frac{k}{C_p}; \quad \overline{V}^2 = \frac{\overline{\tau}}{\overline{\tau}}. & (15) \\ & [8]. \end{bmatrix}$$

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$$\begin{bmatrix} 5 \end{bmatrix} (\dots, 1 \dots) \qquad T: \\ \frac{\partial T}{\partial t} = t' \cdot \Delta T - \frac{t'}{(v')^2} \cdot \frac{\partial^2 T}{\partial t^2}; \ t' = \frac{t'}{(v')^2} = \frac{\left(\frac{1}{c^2} + y_1 \cdot \frac{x}{(\frac{1}{2} + 2^-)}\right)}{\left(\frac{1}{c_0^2} + y_0 \cdot \frac{x}{(\frac{1}{2} + 2^-)}\right)}; \qquad (16)$$

$$(v')^2 = \left(c^{-2} + y_1 \cdot \frac{x}{(\frac{1}{2} + 2^-)}\right)^{-1}. \qquad , \qquad \\ \begin{bmatrix} 5 \end{bmatrix} \quad T: & , \qquad , \\ \frac{\partial T}{\partial t} = t^* \cdot \Delta T - t_0 \cdot \frac{\partial^2 T}{\partial t^2}, \ t^* = c^2, \qquad (17) \\ t_0 - & (\dots), \\ \vdots & \\ t_M & , \\ t_M & , \\ t_M & \\ (& y \ge 0 \\ v, & \frac{\partial v}{\partial t}, T & \frac{\partial T}{\partial t}, \\ y : & \frac{\partial^2 T}{\partial t^2} - \frac{1}{t_M} \cdot \int_0^1 \exp\left\{-\frac{t-\epsilon}{t_M}\right\} \cdot \frac{\partial^2 v}{\partial y^2} d\zeta = \frac{1}{a^2} \cdot \frac{\partial^2 v}{\partial t^2} + \frac{r}{(\frac{1}{2} + 2^-)} \cdot \frac{\partial T}{\partial y}, \qquad (18) \\ \frac{\partial^2 T}{\partial y^2} = \frac{1}{t^*} \cdot \left(t_0 \cdot \frac{\partial^2 T}{\partial t^2} + \frac{\partial T}{\partial t}\right), \ t_M = \frac{y^*}{E}, \ a^2 = \frac{1 + 2^-}{m}, \qquad (19) \\ y^* - & , \qquad , \qquad , \end{cases}$$

$$\begin{pmatrix} (&) \\ - & Z \end{pmatrix} = (& (& -) \\ \frac{\partial^{2}T}{\partial z^{2}} - \frac{1}{a_{0}^{2}} \cdot \frac{\partial^{2}T}{\partial t^{2}} = \frac{1}{a_{0}^{2} \cdot t_{0}} \cdot \frac{\partial T}{\partial t}, \qquad (20)$$

$$a_{0}, t_{0} - & (&), \\ \vdots & \vdots & \vdots \\ (&), a_{0} \end{pmatrix} = (& (&), \\ a_{0}^{2} = \bar{V}^{2} = \frac{t}{t_{0}} = \frac{1}{t_{0} \cdot c_{-} \cdot \dots}, \qquad c_{-} - \\ (&), | - & , t_{-} \\ (&), | - & , t_{-} \\ (&), | - & , t_{-} \\ (&), | - & , t_{-} \\ f, t, y: \\ T = T_{0} \cdot f; t = \frac{t}{T}; y = \frac{z}{\bar{V} \cdot T}; T_{-} = 2 \cdot t_{0}, \qquad (21)$$

$$T_{0} - & (&). \\ (20) \qquad \vdots \\ \frac{\partial^{2}f}{\partial y^{2}} - \frac{\partial^{2}f}{\partial t^{2}} = 2 \cdot \frac{\partial f}{\partial t}. \qquad (22)$$

$$(22) \qquad (14). \qquad (& (22)) = \frac{1}{2}$$

$$3. \qquad (&), \\ [9] \qquad (& \dots), \\ (&), \\ ($$

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[9] ,

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[10]. ,)

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 $\mathbf{v} = \frac{\partial u}{\partial x} = \frac{\mathbf{\tilde{t}}}{E} + k_T \cdot \mathbf{w},$ (29)

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$$\ddagger_0 \cdot \frac{\partial^2_{n}}{\partial t^2} + \frac{\partial_{n}}{\partial t} = \ddagger \cdot \frac{\partial^2_{n}}{\partial x^2} - \$' \cdot \frac{\partial^2 u}{\partial x \partial t}.$$
(30)

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 $\mathsf{t} = \frac{|}{C_v \cdot \dots}, \ \mathsf{s}' = \frac{k_T \cdot E \cdot \Theta}{C_v \cdot \dots},$ (31)

 $\begin{cases} \ddagger_{0} \cdot \frac{\partial^{2}_{u}}{\partial t^{2}} + \frac{\partial_{u}}{\partial t} - \ddagger \cdot \frac{\partial^{2}_{u}}{\partial x^{2}} + \texttt{S}' \cdot \frac{\partial^{2} u}{\partial x \partial t} = 0, \\ \frac{\partial^{2} u}{\partial x^{2}} - k_{T} \cdot \frac{\partial_{u}}{\partial x} - \frac{1}{c_{s}^{2}} \cdot \frac{\partial^{2} u}{\partial t^{2}} = 0, \end{cases}$ (32) $c_s = \sqrt{\frac{E}{\dots}} - -$ ().

[10] [10] , p = p(t) -:

> $p = E \cdot \left(\frac{\partial u}{\partial x} - k_T \cdot \mu\right).$ (33)

> > W

) [10] f.

$$\begin{array}{c} & & & & & \\ & & & & \\ & & & \\ & & & \\ & & & \\ &$$

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$$p^*/p$$
 [10] ,
 $<_{max}$ $x = L/2$, -
) x^*, \pm -

\ddagger_0/T	0,1	1	10
* "	0,272	0,15	0,027
‡ .	0,396	0,72	3,96

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[11] [3], , ,

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$$u_{0,c\dagger} + \frac{(1-\overline{z}^{2})^{1/2}}{2} \cdot \left(1 + \frac{r_{4} \cdot A}{l \cdot V}\right) \cdot u_{0,c} \cdot u_{0,c} - \left[\frac{\overline{z}^{2}}{2} + \frac{r_{1} \cdot (1-\overline{z}^{2})}{2 \cdot l \cdot V}\right] \cdot u_{0,c,c} - \frac{(1-\overline{z}^{2})^{1/2}}{2 \cdot l \cdot V} \cdot \left\{\overline{z}^{2} + \frac{r_{2} + r_{3} \cdot (1-\overline{z}^{2})}{l^{2} \cdot V}\right\} \cdot u_{0,c,c,c} = 0,$$

$$r_{i}, \ i = \overline{(1,4)} \qquad :)$$

$$(i = 2,3);)$$

$$(i = 4); \ l - \frac{1}{2}; \ \overline{z} - \frac{$$

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$$V = \sqrt{\frac{E \cdot g}{x \cdot (1 - \overline{z}^{2})}}; E - (y); x - (y);$$

(*M*) . ,
$$0 < M << 1$$

(*v* = $u_{0):$

$$v = 3 \cdot W \cdot \sec h^2 \left[\sqrt{\frac{W}{4 \cdot B}} \cdot \left(\langle -W \cdot \ddagger \right) \right], \tag{37}$$

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$$W - ,$$

$$v(\infty) = 0, \quad v(-\infty) = v_1 \qquad :$$

$$W = \frac{1}{2}v_1 = \frac{1}{2}\Delta v, \quad \Delta v = v_1(-\infty) - v(\infty).$$
(38)

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