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### Buchholz's

$$S_B = |U| |I| \quad (1)$$

( . . ) 3-

$$|I| = \sqrt{I_a^2 + I_b^2 + I_c^2}, \quad |U| = \sqrt{U_a^2 + U_b^2 + U_c^2} \quad (2)$$

(3D- )

$$\mathbf{U} = \begin{bmatrix} \dot{U}_a \\ \dot{U}_b \\ \dot{U}_c \end{bmatrix} = \begin{bmatrix} U_a e^{j\omega t} \\ U_b e^{j\omega t} \\ U_c e^{j\omega t} \end{bmatrix}, \quad \mathbf{I} = \begin{bmatrix} \dot{i}_a \\ \dot{i}_b \\ \dot{i}_c \end{bmatrix} = \begin{bmatrix} I_a e^{j\omega t} \\ I_b e^{j\omega t} \\ I_c e^{j\omega t} \end{bmatrix} \quad (3)$$

(3)

$$\mathbf{U} = \frac{\sqrt{2}}{T} \int_0^T \mathbf{u}(t) e^{-j\omega t} dt, \quad \mathbf{I} = \frac{\sqrt{2}}{T} \int_0^T \mathbf{i}(t) e^{-j\omega t} dt \quad (4)$$

$$\mathbf{u}(t) = \begin{bmatrix} u_a(t) \\ u_b(t) \\ u_c(t) \end{bmatrix}, \quad \mathbf{i}(t) = \begin{bmatrix} i_a(t) \\ i_b(t) \\ i_c(t) \end{bmatrix} \quad (5)$$

3D-

$$\dot{S} = U \cdot I^* = \dot{U}_a I_a^* + \dot{U}_b I_b^* + \dot{U}_c I_c^* \quad (6)$$

$$S_G = |U \cdot I^*| \quad (7)$$

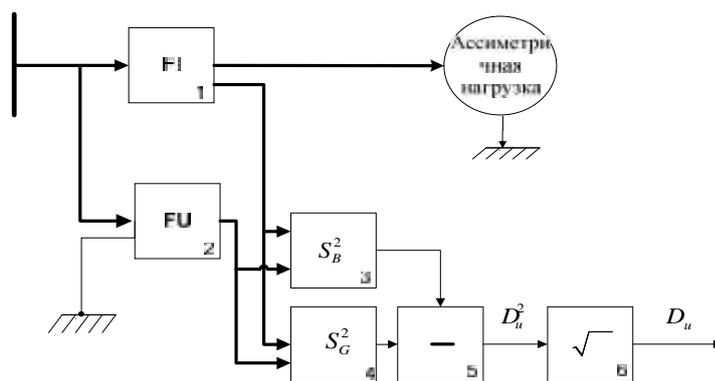
$$S_B \geq S_G$$

$$S_B^2 = S_G^2 + D_u^2 \quad (8)$$

$D_u$

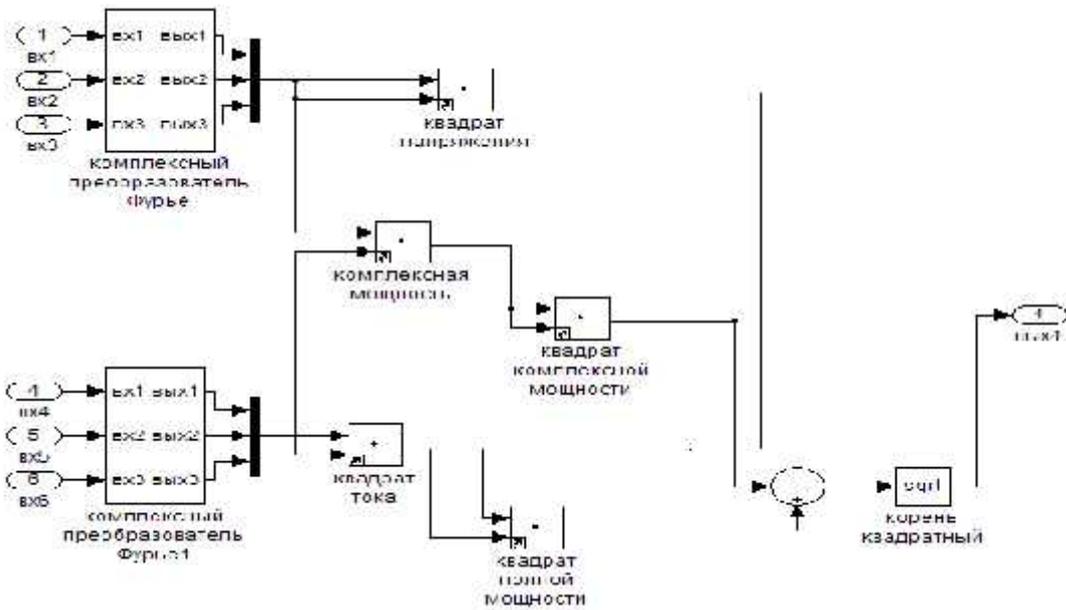
$$D_u = \sqrt{S_B^2 - S_G^2}$$

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Simulink:



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: 1. // . 2009. 6. . 22-27: 2009. 7. . 15-21, <http://www.kudrinbi.ru>. 2. //« », VI , EPQ-2008: C . . : . , .211-214.

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